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Comparison of aerosol chemistry transport model simulations with lidar and Sun photometer observations at a site near Paris

A. Hodzic,¹ H. Chepfer,¹ R. Vautard,¹ P. Chazette,² M. Beekmann,³ B. Bessagnet,⁴ B. Chatenet,⁵ J. Cuesta,¹ P. Drobinski,³ P. Goloub,⁶ M. Haeffelin,¹ and Y. Morille¹

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[1] The ability of the aerosol chemistry transport model CHIMERE to simulate the vertical aerosol concentration profiles at a site near the city of Paris is evaluated using routine elastic backscatter lidar and Sun photometer measurements. The comparisons of model aerosols with measurements are carried out over a full year time period between October 2002 and September 2003. The methodology we propose here is new: From the model concentration outputs (optical properties varying with chemical composition and mass vertical distribution) we simulate the lidar backscattering profiles and compare them with the observed ones. The comparisons demonstrate the ability of the model to reproduce correctly the aerosol vertical distributions and their temporal variability. However, the aerosol load within the boundary layer is generally underestimated by the model, in particular during the afternoon hours and the summertime period. Several sensitivity tests indicate that this underestimation may have two origins: the lack of secondary organic and, to a lesser extent, mineral aerosols inside the model. The second deficiency is due to the absence of erosion/resuspension of soil material in the primary aerosol sources considered here; the first deficiency is probably due to incomplete knowledge about the formation of organic species in a photochemically active atmosphere. The results also show that the particles ranging from 0.08 to 1.25 μm in radius represent more than 89% of the volume backscattering at 532 nm, while the coarse particles are not efficient in terms of optical properties. The missing aerosol mass must therefore be found within the accumulation mode.

INDEX TERMS: 0305 Atmospheric Composition and Structure: Aerosols and particles (0345, 4801); 0345 Atmospheric Composition and Structure: Pollution—urban and regional (0305); 0394 Atmospheric Composition and Structure: Instruments and techniques; *KEYWORDS:* aerosol modeling, aerosol optical properties, lidar profile, model validation, vertical distribution of aerosols

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1. Introduction

[2] In the lower troposphere anthropogenic aerosols have a significant impact on health and visibility [e.g., Bennet *et al.*, 1985; Lurmann *et al.*, 1997; Eleftheriadis *et al.*, 1998] especially in the vicinity of large cities like Paris where aerosols may result both from direct emissions and from secondary formation. Their concentration and composition vary spatially and temporally because of numerous sources, meteorological conditions and aerosol dynamical processes,

such as nucleation, condensation, evaporation, and coagulation. Some of them are not completely understood today. In order to improve our knowledge and quantify the aerosol impact on the environment, aerosol monitoring and modeling have become a real scientific challenge.

[3] In order to predict aerosol concentrations during pollution events, to understand the processes involved and to test the theoretical knowledge about these processes against observations, scientists have developed complex, fully three-dimensional (3-D) air quality models. Most of these models now include the particulate matter components and the associated physics and chemistry [Hass *et al.*, 2003]. The chemistry transport models (CTMs) have been extensively tested against ozone and other gas-phase concentration observations, but the evaluation of the aerosol components is largely incomplete. In Europe, the most comprehensive evaluation has been conducted by Hass *et al.* [2003] comparing simulations from six models of different complexity of the aerosol module (bulk, modal, sectional approach) to surface measurements of inorganic ions gathered from the EMEP and national air quality networks during April to September 1995. For sulfate and ammonium

¹Laboratoire de Météorologie Dynamique, Institut Pierre-Simon Laplace, Palaiseau, France.

²Laboratoire des Sciences du Climat et de l'Environnement, Institut Pierre-Simon Laplace, Gif sur Yvette, France.

³Service d'Aéronomie, Institut Pierre-Simon Laplace, Paris, France.

⁴Institut National de l'Environnement Industriel et des Risques, Verneuil en Halatte, France.

⁵Laboratoire Interuniversitaire des Systèmes Atmosphériques, Créteil, France.

⁶Laboratoire d'Optique Atmosphérique, Lille, France.

particles, most of the comparisons for station averages fall within a factor of two without a systematic bias (taking the six models altogether). Nitrate is systematically overestimated by models. The CHIMERE model used in this study shows normalized errors between 50 and 80% for inorganic ions and 40–90% for PM_{10} (particles smaller than 10 μm), in comparison to summer 2000 data. Systematic comparison of other aerosol components such as soot and organic carbon has not yet been performed in Europe. The evaluation of the space-time variability of the aerosol concentration simulated by 3-D aerosol CTMs is therefore fairly incomplete and further efforts of model evaluation have to be made.

[4] Aerosol lidar measurements represent another type of available data in a great number of sites [Bösenberg *et al.*, 2003]. Today, these data are not used for the validation of aerosol chemistry transport models near urban areas, mainly because the retrieval of the aerosol concentration from the lidar signal is still difficult, since there is no one-to-one correspondence between the lidar backscatter signal and the aerosol concentration, because backscattering properties of the aerosol mixture depends on its composition and on relative humidity [Hänel, 1976]. However, it is possible to link the chemical composition of the aerosol to its optical properties through the refractive index which is known for the major aerosol components [Chazette and Lioussé, 2000]. Some studies have been carried out for characterizing urban aerosols using lidar observations over the Tessaloniki area [e.g., Balis *et al.*, 1999]. Also, lidar measurements have been used for the evaluation of desert dust aerosol transport forecast models [Guelle *et al.*, 2000; Ansmann *et al.*, 2003], but lidar measurements have never been used for the validation of aerosol pollution models. Elastic and inelastic backscatter lidar profiles contain valuable information on the vertical distribution of aerosol layers. When these lidar profiles are taken at the same site over a long time period (several days or months), they provide the basis for a statistical validation of the model, which allows a better understanding of the transport and mixing processes over a variety of meteorological situations [Bösenberg *et al.*, 2003].

[5] Sun photometers also bear a complementary potential for aerosol chemistry transport model validation. Under clear-sky conditions, these instruments measure the integrated optical properties of the aerosols present in the atmospheric column (optical thickness, scattering albedo and complex refractive index). Sun photometer measurements are now taken routinely in the Aerosol Robotic Network (AERONET) (available at <http://aeronet.gsfc.nasa.gov>) [Holben *et al.*, 1998]; therefore numerous measurements are available in several sites over the globe. Sun photometer measurements are very important constraints for the lidar inversion procedure as shown during INDOEX (Indian Ocean Experiment) by Pelon *et al.* [2002] or Chazette [2003]. They are also important to validate spaceborne observations [e.g., Moulin *et al.*, 1997]. Nevertheless, so far these measurements have mostly been used for the validation of global mineral aerosol transport models [e.g., Guelle *et al.*, 2000].

[6] In this article, we use the quasi-continuous measurements taken at the “Site Instrumental de Recherche par Télédétection Active” (SIRTA) [Haeffelin *et al.*, 2003] in order to assess the ability of the aerosol chemistry transport model CHIMERE [Bessagnet *et al.*, 2004; Schmidt *et al.*, 2001] to simulate the space-time variability of the aerosol

concentrations in a suburban environment. This paper is also designed to propose a new model validation methodology using elastic lidar measurements by directly simulating the lidar signal from the model outputs and comparing the resulting profiles to the observed actual lidar signals. The optical properties of the model aerosols are compared, in a statistical manner, to measurements obtained with a Sun photometer of the AERONET network also located at the SIRTA site. All these comparisons are made over several tens of days spread over a full year. Differences between summertime and wintertime results are discussed. In section 2, the chemistry transport model CHIMERE and its aerosol module are briefly described. In section 3 the available observations are presented. Section 4 describes the method used for the comparison of observed and modeled data, and finally the results of the comparison with Sun photometer and lidar are presented and discussed in sections 5 and 6. Section 7 contains our conclusions.

2. Model Description

2.1. General Model Configuration

[7] CHIMERE is a 3-D chemistry transport model that simulates gas-phase chemistry [Schmidt *et al.*, 2001; Vautard *et al.*, 2001], aerosol formation, transport, and deposition [Bessagnet *et al.*, 2004] at European and urban scales. It has been designed with the aim of performing both episodic and long-term simulations at various spatial scales ranging from local to regional scale, on a personal computer or a workstation. The latest versions of the model and their documentation are available for download on the Web site <http://euler.lmd.polytechnique.fr/chimere>. The general performances of the model for the simulation of ozone and aerosols are given by Schmidt *et al.* [2001], Vautard *et al.* [2001], and Bessagnet *et al.* [2004] and also in a more recent application over Bangkok (B. Zhang *et al.*, Comparison of the UAM-V/SAIMM and CHIMERE/ECMWF photochemical modeling system performance in a tropical urban area, submitted to *Journal of the Air and Waste Management Association*, 2004). The model has also been used for other applications such as sensitivity to emissions [Derognat *et al.*, 2003; Menut, 2003; Schmidt and Martin, 2003; Sillman *et al.*, 2003] or ozone data assimilation [Blond *et al.*, 2003, Blond and Vautard, 2004].

[8] In the present application, the model is run at meso-scale in a domain covering the Paris greater metropolitan area (Figure 1). The model domain is described by Vautard *et al.* [2001, 2003]. It is 150 km wide with a 6-km grid size resolution. Compared to previous studies, vertical resolution of the small-scale model version is increased to 20 sigma-pressure levels extending up to 500 hPa that covers the boundary layer and the lower part of the free troposphere.

[9] Boundary conditions are provided by a prior regional, large-scale simulation using a model configuration similar to that used by Bessagnet *et al.* [2004]. In this case the model domain covers Western Europe with a 0.5° resolution. The vertical resolution of this large-scale configuration is also coarse, with eight vertical levels also extending from ground to 500 hPa. As in the Vautard *et al.* [2003] work we use a one-way nesting procedure. Boundary conditions of regional simulations are taken from climatologies of the MOZART global chemistry transport model [Horowitz *et al.*

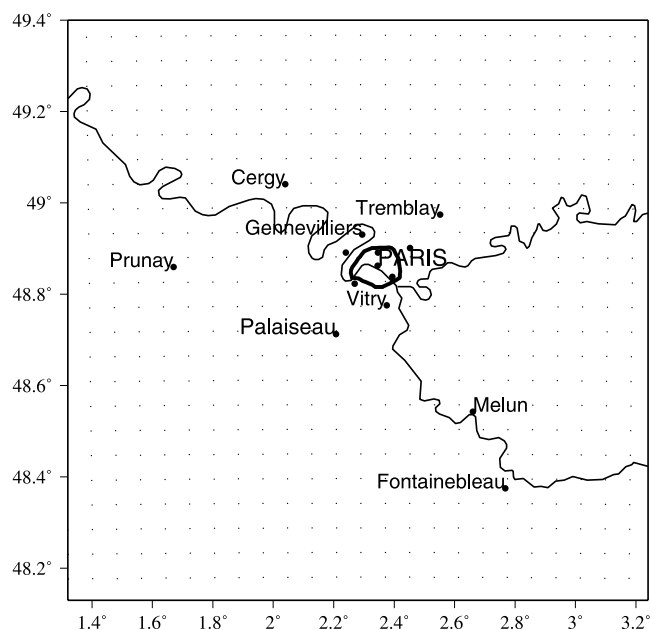


Figure 1. The model horizontal grid (dots) and domain. A few sites where air quality is monitored by the AIRPARIF network are indicated on the figure, as well as the site where lidar observations are made (Palaiseau).

al., 2003]. For aerosol species, zero concentrations are assumed at outer boundaries.

[10] The model simulates the concentration of 44 gaseous species and 6 aerosol chemical compounds. The gas-phase chemistry scheme [Lattuat, 1997] has been extended to include sulfur aqueous chemistry, secondary organic chemistry and heterogeneous chemistry of HONO [Aumont *et al.*, 2003] and nitrate [Jacob, 2000].

2.2. Aerosol Module

[11] The population of aerosol particles is represented using a sectional formulation, assuming discrete aerosol size sections and considering the particles of a given section as homogeneous in composition (internally mixed). Like in the work of Bessagnet *et al.* [2004], we use six diameter bins ranging between 10 nm and 40 μm , with a geometric increase of bin bounds. The aerosol module accounts for both inorganic and organic species, of primary or secondary origin, such as, primary particulate matter (PPM), sulfates, nitrates, ammonium, secondary organic species (SOA) and water. PPM is composed of primary anthropogenic species such as elemental and organic carbon and crustal materials. In the model, ammonia, nitrate, and sulfate are considered in aqueous, gaseous, and particulate phases.

[12] Sulfate is produced from gaseous and aqueous oxidation of SO_2 [Berge, 1993; Hoffman and Calvert, 1985; Lee and Schwartz, 1983]. Nitric acid is produced in the gas phase by NO_x oxidation, but also by heterogeneous reaction of N_2O_5 on the aerosol surface [Jacob, 2000]. Issued directly from primary emissions, ammonia is converted into aerosol phase (mainly ammonium-nitrate and ammonium-sulfate) by neutralization with nitric and sulfuric acids. Secondary organic aerosols are formed by condensation of biogenic and anthropogenic hydrocarbon oxidation products, they are partitioned between the aerosol and gas

phase through a temperature-dependent partition coefficient [Pankow, 1994]. A lookup table method, set up from the ISORROPIA equilibrium model [Nenes *et al.*, 1998, 1999], is used to calculate concentrations at equilibrium for inorganic aerosols composed of sulfate, nitrate, ammonium, and water. Dynamical processes influencing aerosol population are also described. New particles are formed by nucleation of H_2SO_4 [Kulmala *et al.*, 1998]. Particles' growth due to the coagulation and condensation of semivolatile species is also taken into account. The coagulation process applied for multicomponent system is calculated as in the work of Gelbard and Seinfeld [1980]. Aerosols can be removed by dry deposition [Seinfeld and Pandis, 1998] and wet removal [Guelle *et al.*, 1998; Tsyro, 2002]. Particles can be scavenged either by coagulation with cloud droplets or by precipitating drops. Moreover, particles act efficiently as cloud condensation nuclei to form new droplets.

2.3. Meteorological Forcing

[13] CHIMERE requires several meteorological variables as input. These are wind, temperature, mixing ratio for water vapor and liquid water in clouds, 2 m temperature, surface heat and moisture fluxes and precipitation. In previous CHIMERE applications, meteorological fields from the European Centre for Medium-Range Weather Forecasts were used. Owing to the relatively high resolution required for the present application, we use a mesoscale meteorological model, MM5 [Dudhia, 1993], in order to force the CHIMERE simulations. Meteorological mesoscale simulations are performed with a two-way nesting procedure with two domains of respective resolutions 15 km and 5 km. The smallest meteorological domain encompasses the CHIMERE domain. In order for the synoptic flow to stay close to meteorological analyses, the 15-km resolution meteorological simulation uses nudging for all variables with a coefficient of 10^{-4} s^{-1} . Regional CHIMERE simulations are forced by regional simulations using MM5 with a 36-km resolution.

2.4. Emissions

[14] For the large-scale simulations, the anthropogenic emissions for NO_x , CO, SO_2 , NMVOC and NH_3 gas-phase species for 10 anthropogenic activity sectors (as defined by the SNAP categories) are provided by EMEP (available at <http://www.emep.int>) with spatial resolution of 50 km. Emissions of primary particulate matter PM_{10} and $\text{PM}_{2.5}$ are taken from the TNO (Netherlands Organization for Applied Scientific Research) European inventory (available at <http://www.air.sk/tno/cepmeip/>).

[15] For the local-scale simulations around Paris, the gas-phase emission inventory built by the AIRPARIF air quality-monitoring network is used. This emission inventory, valid in principle for year 1998, is described and evaluated by Vautard *et al.* [2003]. However, no inventory of particulate matter emission was available at the time of the study. In order to have physically meaningful PM emissions, we use the regional-scale PM to NO_x annual emission ratios, for each first-level activity sector available in the TNO emissions in the neighborhood of Paris, and apply the same ratios for the small-scale distribution of PM emissions in the Ile-de-France area. PM emissions are therefore spatially distributed exactly as NO_x for each first-level SNAP activity

sector, while PM emission totals are coherent with the EMEP inventory. The use of PM/NO_x ratios instead of ratios to another gaseous species is motivated by the assumption that most of the urban aerosol emissions are of small size and come from combustion and more particularly from the road traffic sector.

2.5. Model Simulations

[16] The model is run in time slices of five consecutive days with full restarts, so that the concentrations are continuous in time. Both regional and small-scale versions are run in this way. This whole set of simulations starts on 28 September 2002 and ends on 2 October 2003. It is initialized with a first spin-up run of 3 days. A small period of time, from 1 January to 9 February 2003 is not simulated because of missing NCEP analyses in our database.

3. Experimental Setup

[17] Measurements used in this comparison have been performed quasi continuously in Palaiseau, in the south-western suburb of Paris (2.208°E, 48.713°N), France, by two different instruments, an elastic backscatter lidar and a Sun photometer, at the French observatory SIRTa [Haefelin *et al.*, 2003] initiated by Institut Pierre-Simon Laplace (IPSL). Routine measurements at SIRTa offer an exceptional framework to compare model simulations and observations over long time periods.

3.1. Elastic Backscatter Lidar

[18] The elastic backscatter lidar provides routine measurements at 532 nm since year 2000, in the frame of the European lidar network EARLINET [Bösenberg *et al.*, 2003]. The lidar system is based on Nd-YAG pulsed laser emitting at 1064 nm. The emission frequency is doubled (532 nm) and linearly polarized. Backscattered photons are collected through a large narrow-field-of-view (NFOV) telescope that ranges from ground to 15 km and smaller wide-field-of-view (WFOV) telescope that ranges from ground to 6 km. Vertical raw resolution is of 15 m. The laser pulse repetition frequency is 20 Hz and the temporal sampling is made every 10 s, with power of 100 mJ pulse⁻¹. It is important to notice that the lidar signal must be corrected from the overlap factor below about 800 m caused by the incomplete overlap between the telescope and the laser beam [e.g., Sicard *et al.*, 2002; Chazette, 2003]. This factor can be estimated from the lidar system characteristics given in Table 1.

[19] Each raw lidar vertical profile is normalized to the molecular signal at an aerosol-free level following the method proposed by Fernald *et al.* [1972]. The altitude of normalization varies with time, but it is registered for each profile to allow comparisons with the simulations (section 6).

3.2. Sun Photometer

[20] Another independent data set comes from a CIMEL 318-CE Sun photometer that has operated at SIRTa since July 2002, as part of AERONET network. The Sun photometer instrument performs measurements of the optical thickness at several wavelengths in the visible spectrum. Data are corrected from cloud contamination. For this study, we derive the optical thickness data at 532 nm from

Table 1. Lidar Characteristics Relative to Overlap Factor Correction^a

System Parameters	Values
Field of view	2 mrad
Laser beam divergence	0.6 mrad
Radius of the emitter beam	3 mm
Diameter of the primary mirror	208 mm
Diameter of the secondary mirror	57 mm
Distance between emitted laser beam and telescope optical axis	60 cm

^aLidar characteristics relative to overlap factor correction for the wide-field-of-view telescope are given.

the 440 and 670 nm channels using the Angström relation [Angström, 1964]:

$$\delta_{532} = \delta_{670} \left(\frac{532}{670} \right)^{-\alpha}, \quad (1)$$

where α is the Angström exponent defined as equation (2)

$$\alpha = \ln \left(\frac{\delta_{440}}{\delta_{670}} \right) / \ln \left(\frac{670}{440} \right). \quad (2)$$

Direct measurement of the aerosol optical thickness gives a maximal absolute uncertainty of 0.02, independent of aerosol load [e.g., Holben *et al.*, 1998]. The relative uncertainty on α is a function of the optical thickness. As proposed by [Hamonou *et al.*, 1999], the relative error on δ_{532} can be expressed as

$$\frac{\Delta \delta_{532}}{\delta_{532}} = \left(1 + \frac{\ln \left(\frac{532}{440} \right)}{\ln \left(\frac{670}{440} \right)} \right) \frac{\Delta \delta_{440}}{\delta_{440}} + \left(\frac{\ln \left(\frac{532}{670} \right)}{\ln \left(\frac{670}{440} \right)} \right) \frac{\Delta \delta_{670}}{\delta_{670}}. \quad (3)$$

In our study the value of $\frac{\Delta \delta_{532}}{\delta_{532}}$ does not exceed 8% in an aerosol layer of $\delta_{440} > 0.3$.

[21] The Angström exponent depends mostly on the aerosol size distribution: Small values correspond to large particles such as sea salt or mineral particles, whereas values between 1 and 2 are found in polluted air masses containing submicron-sized particles such as sulfates, nitrates and carbonaceous aerosol [Lioussé *et al.*, 1995]. As suggested by Dubovik *et al.* [2001], we considered aerosol optical thickness data only when Angström exponent is higher than 0.6. This filtering procedure has the advantage of eliminating all cloud-contaminated data in a conservative manner.

[22] The Sun photometer measurements also allows to determine the aerosol optical properties such as the integrated single-scattering albedo (SSA) at 532 nm, deduced from the channels at 440 and 670 nm using the Dubovik algorithm [Dubovik and King, 2000; Dubovik *et al.*, 2000], and the real (n) and imaginary (k) parts of the refractive index at 673 nm. The analysis showed [Dubovik *et al.*, 2001] that an accurate SSA (within accuracy of 0.03) and refractive index retrievals (errors about 30% for k and 0.04 for n) can be provided only for high aerosol loading ($\delta_{440} > 0.3$). Therefore, in this study only the measurements corresponding to a high aerosol loading are considered.

4. Comparison Methodology

[23] In order to compare aerosol lidar data with model outputs, we use an original approach: The aerosol lidar

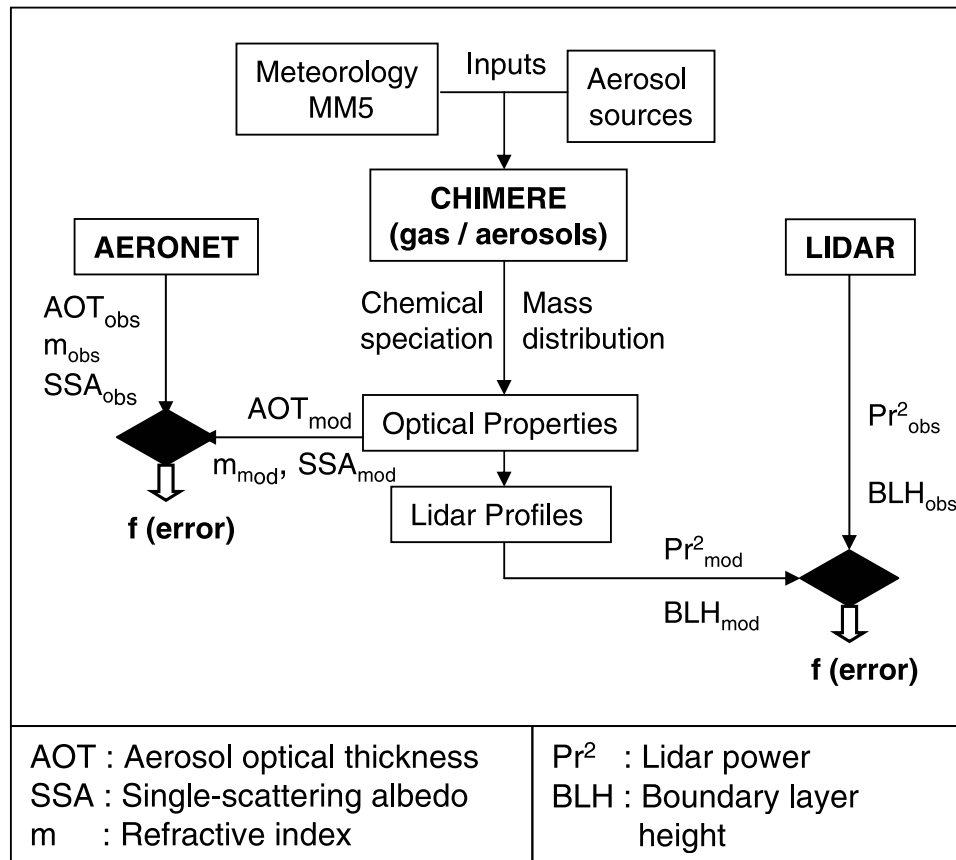


Figure 2. Diagram describing the method of the comparison of the model results with lidar and photometer data.

signal is directly simulated from the model aerosol vertical profiles. More precisely, the lidar equation [Measures, 1984] is solved using the optical properties and the number or the mass concentration of particles in each size section and altitude layer of the model. This approach has the advantage of minimizing the number of assumptions as the simulation of the aerosol lidar signal does not require adding new hypothesis to the ones already used in the model parameterizations. In this section we describe the method used to compute both the aerosol optical properties and the aerosol lidar signal from the model outputs (Figure 2).

4.1. Aerosol Optical Properties

[24] The aerosol and molecular optical properties such as extinction, backscattering coefficients, and backscatter phase function for each size section of the model are computed following the Rayleigh [Ulaby *et al.*, 1943] and Mie [1908] theories of scattering and absorption of electromagnetic radiation by homogeneous spheres. The calculation was done using the calculated model refractive index ($m = n - ik$) associated to the composition of the aerosol in each size bin. In our study we used the refractive index for wet particles in order to take into account the effect of water vapor on hydrophilic aerosols. It was computed from the dry one using the Hänel's [1976] relation:

$$m_{\text{wet}} = m_{\text{H}_2\text{O}} + (m - m_{\text{H}_2\text{O}})(r/r_{\text{wet}})^3 \quad (4)$$

$$r_{\text{wet}} = r(1 - \text{RH})^{-e} \quad (5)$$

where r and r_{wet} are the radius of dry and wet particles, respectively; m and m_{wet} are the corresponding refractive indexes; and RH is the relative humidity. The coefficient e depends on the type of aerosol and is equal to 0.285 for sulfate aerosol and has been established to be equal to 0.25 for particulate organic matter over Tessaioniki by Chazette and Liousse [2000].

[25] This previous value is very close to the sulfate one, and as the Paris aerosol is a mixture of water soluble and carbonaceous compounds, the value $e = 0.285$ is kept hereafter. In any case, the sensitivity test shows that using the value $e = 0.25$ the results will be changed by less than 1%. The dry refractive index used for different aerosol species are given in Table 2 [Mallet, 2003].

4.2. Simulation of Lidar Profile

4.2.1. Lidar Equation

[26] The lidar elastic backscattered signal is defined by the classical lidar equation [e.g., Collis and Russell, 1976]:

$$P(z) \cdot z^2 = C_L \cdot F(z) \cdot (\beta_m(z) + \beta_a(z)) \cdot \exp\left(-2 \cdot \int_0^z (\alpha_m(z) + \alpha_a(z)) dz\right) \quad (6)$$

where C_L is the constant geometric factor depending on the technical characteristics of the emitting and receiving optics (instrumental constant and transmitted energy) and $F(z)$ is the overlap factor that is a function of the emitting and

Table 2. Refractive Index for Different Aerosol Components at 0% of Relative Humidity at Wavelength of 550 nm^a

Aerosols	Real Part n	Imaginary Part k
Primary particulate matter	1.75	0.44
Secondary organic aerosol	1.55	0.05
Water soluble (sulfate, nitrate, ammonium)	1.53	6×10^{-3}
Mineral dust ^b	1.53	5.5×10^{-3}
Sea salt ^b	1.56	6×10^{-3}
Water	1.33	0

^aSource is Mallet [2003].

^bThe mineral dust issued from soil erosion and resuspension and the sea salt are not considered in the model, but they are used in a sensitivity study.

receiving geometry. $F(z)$ is here calculated for a biaxial lidar system with the characteristics given in Table 1 [Lefrère, 1982]; $\beta_m(z)$ and $\beta_a(z)$ are respectively the volume backscattering coefficients for the atmospheric molecules and particles ($\text{m}^{-1} \text{sr}^{-1}$) respectively, while $\alpha_m(z)$ and $\alpha_a(z)$ are the corresponding extinction coefficients (m^{-1}) at altitude z .

[27] The lidar equation is linked to the model outputs by extinction and backscattering coefficients which depend on several parameters, such as the mass distribution of particles n_M ($\text{g cm}^{-3} \text{m}^{-1}$) and their refractive index m related to their composition in each size bin [e.g., Seinfeld and Pandis, 1998]:

$$\alpha_a = \int_0^{R_{\max}} \frac{\sigma_{\text{ext}}(m, r)}{\pi \cdot \rho \cdot r^3} \cdot n_M(r) \cdot dr \quad (7)$$

$$\beta_a = \int_0^{R_{\max}} k_a(r) \cdot \frac{\sigma_{\text{sca}}(m, r)}{\pi \cdot \rho \cdot r^3} \cdot n_M(r) \cdot dr \quad (8)$$

where ρ is the particle density (g cm^{-3}), σ_{ext} and σ_{sca} are the extinction and the scattering cross sections (m^2) of particles, and k_a is the aerosol backscatter phase function (sr^{-1}). The simulated molecular lidar profile is deduced from vertical profiles of temperature and pressure (Trappes radiosounding) using the method described by Collis and Russell [1976].

4.2.2. Normalization of the Simulated Lidar Signal

[28] To compare the simulated lidar profiles with the observed ones, we compute the normalized backscattered power, corrected from the altitude and the geometric overlap:

$$P(z)z_{\text{norm}}^2 = \frac{P(z)z^2}{P(z_{\text{ref}})z_{\text{ref}}^2} = \frac{F(z) \cdot \beta(z)}{\beta_{\text{ref}}(z_{\text{ref}})} \cdot \exp(-2(\delta(z) - \delta_{\text{ref}}(z_{\text{ref}}))) \quad (9)$$

where $\delta(z)$ is the integrated optical thickness due to extinction of lidar signal by the atmospheric molecules and particles. The normalization altitude z_{ref} is taken at the beginning of an aerosol-free area of the atmosphere, where $F(z_{\text{ref}}) = 1$, independently, for each lidar profile ($z_{\text{ref}} > 3 \text{ km}$).

5. Model Validation With the Sun Photometer

5.1. Comparison With AERONET Data

[29] We now compare model outputs with all available cloud-free data from the Aerosol Robotic Network Sun

photometer. The optical properties used for these comparisons are the refractive index, the aerosol optical thickness (AOT) and the single-scattering albedo (SSA). The months during which data were available are indicated in Table 3. Unfortunately, almost no data were available during the fall/winter period because of almost permanent cloudiness. On the model side, optical properties are calculated as averages over the model column, from the ground to 500 hPa. Both observed and simulated monthly mean values are shown together with their respective uncertainty. The error bars correspond to the standard deviation of the monthly mean values, $\pm 2\sigma/\sqrt{N}$, where σ is the standard deviation of the signal and N is the number of available days. For the observations the instrumental error has also been added.

5.1.1. Refractive Index

[30] The refractive index is an instructive indicator of the model behavior because it strongly depends on the aerosol chemical composition and its internal structure. Figure 3 shows the integrated monthly mean refractive index, separated into its real and imaginary parts, at 532 nm for the modeled values and 673 nm for the observed ones. Since the refractive index of the continental aerosol is rather constant in the visible spectrum [Volz, 1973], we can directly compare those values. The observed real part values range from 1.44 to 1.52, while the imaginary part values lie between 0.03 and 0.1. For the real component, the model lies within observed error bars showing a rather good agreement with observations, especially in March and April. For the imaginary component, the differences between simulated and observed values are larger: The model tends to overestimate in winter and spring and to underestimate during summer.

[31] The disagreement between the photometer and the model is probably related to the errors in the aerosol composition. The large uncertainties in the formation of secondary organic aerosols during summer and the lack of mineral dust emission from soil erosion or resuspension are probably the key factors in these discrepancies. Moreover, according to equations (4) and (5), these parameters are also sensitive to relative humidity. A rapid inspection of MM5 humidity profiles as compared with radiosounding reveals an overestimation of the relative humidity by the MM5 model in summer (from 3 to almost 10%) that may be

Table 3. Sun Photometer Measurements in Palaiseau, France, From October 2002 to September 2003

Month	Number of Available Photometer Data					
	Number of Days	Re(m)	Im(m) ^a	SSA	Number of Days	AOT
October 2002	-	-	-	-	17	47
November 2002	-	-	-	-	-	-
December 2002	-	-	-	-	4	17
January 2003	-	-	-	-	-	-
February 2003	5	10	10	10	16	245
March 2003	12	29	29	29	22	585
April 2003	5	17	17	17	26	432
May 2003	6	22	17	17	21	254
June 2003	12	21	20	20	28	355
July 2003	4	10	7	7	27	339
August 2003	16	43	42	42	30	673
September 2003	4	10	10	10	25	612

^aRe(m) is real part of the refractive index; Im(m) is imaginary part of the refractive index.

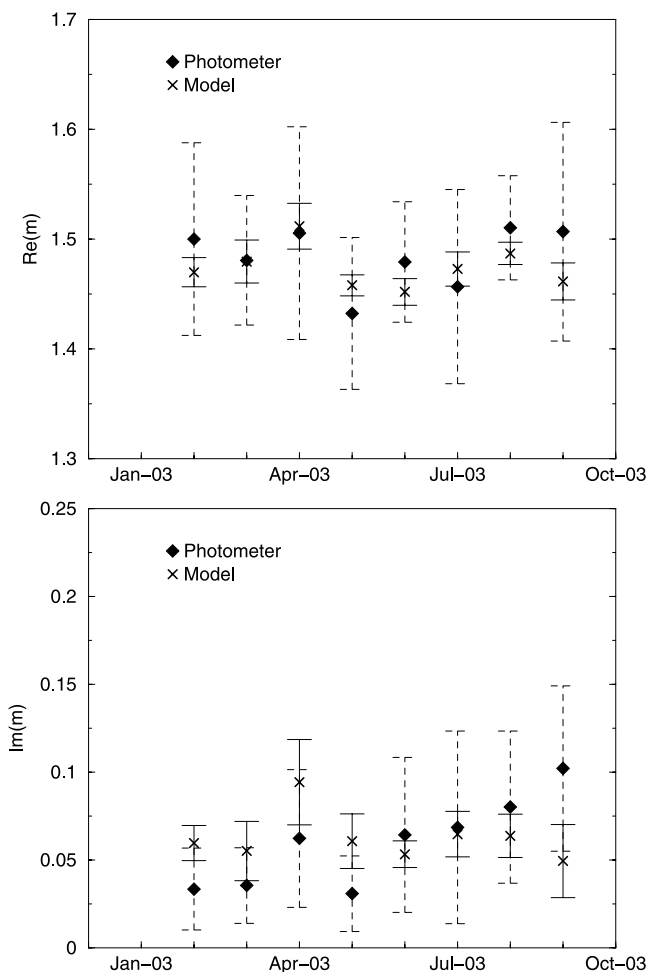


Figure 3. Integrated monthly mean refractive index, (top) real and (bottom) imaginary parts, deduced from Sun photometer measurements at 673 nm and CHIMERE simulations at 532 nm close to Paris (Palaiseau, France) between January and September 2003.

responsible for the underestimation of the refractive index values.

5.1.2. Aerosol Optical Thickness (AOT)

[32] Figure 4 shows the monthly mean values of the aerosol optical thickness observed as well as those simulated by CHIMERE. The observed AOT varies from 0.18 in December and February to 0.34 in August. It is obvious that the model underestimates the observed AOT values in spring and summer (from 20% in March to more than 50% in August), while from October to February the sign of the bias is not clear. The highest values of the optical thickness, greater than 0.5, are observed during stable atmospheric situations favorable to pollution episodes, as for the case of 26 March 2003, discussed in the following, but also during the great pollution episode associated to the heat wave that occurred in Western Europe during the first two weeks of August 2003.

[33] The differences observed between the photometer and the model data result from the uncertainties in the aerosol composition as seen on the refractive index values, but also from the underestimation of the aerosol mass concentrations. The summer bias is most likely related to

an underestimation of secondary organic species by the CHIMERE model: There are large uncertainties in precursor emissions and above all in the chemical processes leading to SOA formation. As previously mentioned the wind resuspended and natural eroded dust particles, which are not taken into account in the model, could significantly contribute to the lack of the aerosol load in spring and summer time periods. This mass underestimation will be confirmed in the next section by the comparison with lidar measurements. We have to notice that the Sun photometer considers the AOT due to the whole atmosphere column, while the model only takes into account the first 5 km, which could also lead to model underestimation, especially in the presence of high-altitude suspended desert aerosols.

5.1.3. Single-Scattering Albedo (SSA)

[34] Another valuable optical indicator of the model behavior is the single-scattering albedo. Figure 5 shows that the model tends to underestimate the observed SSA over the study period, except in September. The observed mean values vary from 0.69 to 0.84, while the simulated ones range from 0.68 to 0.75 with less monthly variability. The bias is particularly important in February, March, and May, months during which the model also indicates an important overestimation of the imaginary part of the refractive index. This suggests that the simulated aerosols are more absorbent than the observed ones especially during winter and spring months.

[35] The comparison with AERONET data shows that aerosol optical parameters are rather correctly reproduced, on average, by CHIMERE for the considered period. We conclude that the model optical parameters can be used to compute backscattering profiles for the comparison with the lidar measurements.

5.2. Sensitivity Study of the AOT

[36] In this section we try to identify possible model deficiencies by performing sensitivity tests. First of all, size sections are not equally contributing to the total AOT. Table 4 shows that, for each month, more than 89% of

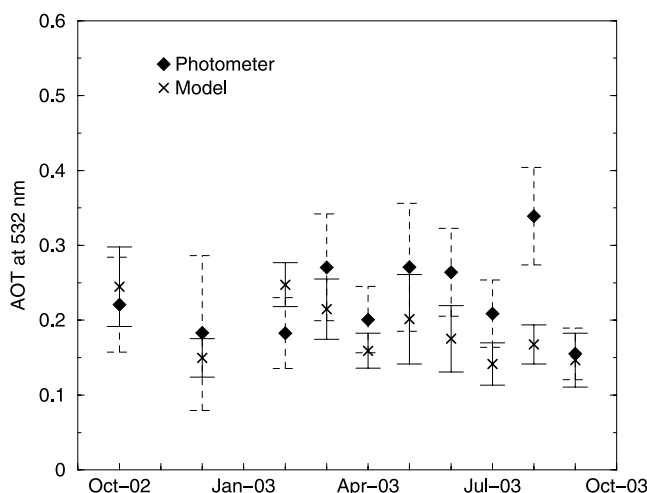


Figure 4. Monthly mean aerosol optical thickness at 532 nm, issued from Sun photometer measurements and CHIMERE simulations at Palaiseau, France, between October 2002 and September 2003.

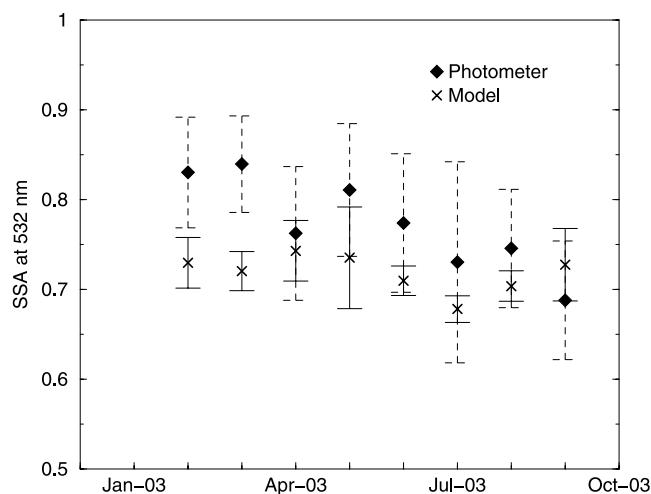


Figure 5. Monthly mean single-scattering albedo at 532 nm, issued from Sun photometer measurements and CHIMERE simulations at Palaiseau, France, between January and September 2003.

the integrated optical thickness is due to the accumulation mode (model sections 3 and 4) corresponding to aerosol radius from 0.08 to 1.25 μm . The nucleation and the coarse modes have a smaller effect, less than 4% and 7%, respectively. These results are in good agreement to those found during the ESQUIF campaign over Paris (P. Chazette et al., Optical properties of urban aerosol from airborne and ground in situ measurements performed over Paris area, the ESQUIF program, submitted to *Journal of Geophysical Research*, 2004). A possible bias in the aerosol mass must therefore be sought in this mode.

[37] Second, Bessagnet et al. [2004] demonstrated the ability of the model to simulate nitrate, sulfate, and ammonium aerosol compounds, although they only used ground-level observations for the comparisons. A good candidate aerosol class for the AOT bias is the SOA class, because it is mainly located in the accumulation mode and because a comparison of simulations and observations for this class has not yet been possible. By trial and error, we found that multiplying by three the mass of the model

SOA compound provides a fairly good match between simulated and observed lidar signals especially during spring and summer months (see section 6). In the case of AOTs, the monthly mean predictions rise on average from 7% in winter to 28% in summer, and the normalized biases decrease from 4% in December to more than 20% in June (Table 5). However, the increase of the SOA during autumn and winter (except in December) contributes to the overestimation of photometer-derived AOT values, and the results are not improved. The increase in the SOA mass undeniably allows a better agreement between the observed and simulated AOT values in spring and summer period, but underestimation still remains (close to 15% in July and 36% in August).

[38] Furthermore, missing sources such as mineral compounds or sea salt can also contribute to the underestimation of the model aerosol mass. Putaud et al. [2003] propose an average composition of aerosol based on ground measurements in Europe: In “near city” sites the mineral dust accounts for 7% and 22% in fine (particles smaller than 2.5 μm) and coarse fraction (particles greater than 2.5 μm), respectively, while the sea salt contributes for 3% and 9%, respectively. Adding these contributions to the simulated aerosol total mass would improve the results compared to the reference simulation, except in October and February: The monthly mean values increase from 6% to 10%, and the normalized biases decrease from 4% to 11%.

6. Comparisons With Lidar Vertical Profiles

6.1. Case of 26 March 2003

[39] In order to compare the model with the aerosol lidar data, a case study is first carried out. The pollution episode of 26 March 2003 is chosen to illustrate our comparison. The episode is characterized by stable windless anticyclonic conditions over France, favoring the formation of aerosol pollution. Figure 6 shows a map of mean PM_{10} concentrations simulated by CHIMERE over the Paris area between 1100 and 1600 UTC, together with the AIR-PARIF ground stations corresponding measurements (indicated by the little square boxes on the map). The formation of a PM_{10} plume is observed in the southwest of Paris, with mean concentrations greater than 50 $\mu\text{g m}^{-3}$. The comparison with ground stations principally located

Table 4. Contribution of Each Section of the Model to the Mean AOT at 532 nm^a

Month	Percentage of mean AOT at 532 nm (%)					
	Section 1 (0.005–0.02 μm)	Section 2 (0.02–0.08 μm)	Section 3 (0.08–0.3 μm)	Section 4 (0.3–1.25 μm)	Section 5 (1.25–5 μm)	Section 6 (5–20 μm)
October 2002	0.0	3.7	68.3	24.1	3.8	0.1
November 2002	-	-	-	-	-	-
December 2002	0.0	3.0	74.5	21.1	1.4	0.0
January 2003	-	-	-	-	-	-
February 2003	0.0	3.2	77.0	18.3	1.5	0.0
March 2003	0.0	2.2	73.8	22.2	1.8	0.0
April 2003	0.1	3.8	72.0	22.3	1.8	0.0
May 2003	0.0	2.1	66.9	26.8	4.1	0.1
June 2003	0.0	3.4	65.1	26.5	4.9	0.1
July 2003	0.0	3.7	64.3	27.2	4.7	0.1
August 2003	0.1	3.6	59.8	29.6	6.8	0.1
September 2003	0.0	4.0	64.1	27.8	4.1	0.0

^aContributions are given in percent. The limit radius of each section is indicated in parentheses.

Table 5. Comparison of Observed and Simulated AOTs for the Reference Scenario (1), the Scenario (2) With SOA Increased by 300%, and the Scenario (3) Including Mineral Dust and Sea Salt

AOT, 532 nm	<i>O</i>	Reference 1			Scenario 2			Scenario 3		
		<i>M</i>	Normalized Bias, ^a %	RMS	<i>M</i>	Normalized Bias, ^a %	RMS	<i>M</i>	Normalized Bias, ^a %	RMS
October 2002	0.223	0.245	9.9	0.087	0.281	26.0	0.113	0.268	20.2	0.100
November 2002	-	-	-	-	-	-	-	-	-	-
December 2002	0.183	0.149	-18.6	0.101	0.156	-14.8	0.095	0.159	-13.1	0.099
January 2003	-	-	-	-	-	-	-	-	-	-
February 2003	0.183	0.247	35.0	0.109	0.270	47.5	0.123	0.267	45.9	0.125
March 2003	0.271	0.215	-25.8	0.111	0.255	-5.9	0.101	0.231	-14.8	0.103
April 2003	0.201	0.159	-20.9	0.093	0.185	-8.0	0.087	0.170	-15.4	0.091
May 2003	0.277	0.201	-27.4	0.141	0.242	-12.6	0.126	0.222	-19.9	0.140
June 2003	0.262	0.175	-33.2	0.159	0.229	-12.6	0.190	0.189	-27.9	0.157
July 2003	0.209	0.142	-32.1	0.111	0.177	-15.3	0.125	0.151	-27.8	0.108
August 2003	0.339	0.168	-50.4	0.226	0.217	-36.0	0.205	0.181	-46.6	0.218
September 2003	0.155	0.147	-5.2	0.091	0.182	17.4	0.114	0.157	1.3	0.098

^aBias (%) is computed as follows: normalized bias (%) = $100 \sum_i (M_i - O_i) / \sum_i (O_i)$; the root mean square is defined as $RMS = \sqrt{\frac{1}{N} \sum_i (M_i - O_i)^2}$; where N is the number of samples given in Table 3 for each month, O_i are the observations and M_i are the simulations.

near the city of Paris shows a good agreement between model simulations and ground measurements. However, the site of Prunay, located in the western part of the domain (see Figure 1), was also equipped with a reference instrument for PM₁₀ measurement (PARTISOL). For the

meteorological conditions encountered (temperature from 15°C to 20°C), using the PARTISOL working at 20°C instead of TEOM instrument operating at 50°C, should provide more accurate measurements of PM₁₀ because it avoids the evaporation of semivolatile species. Indeed, the

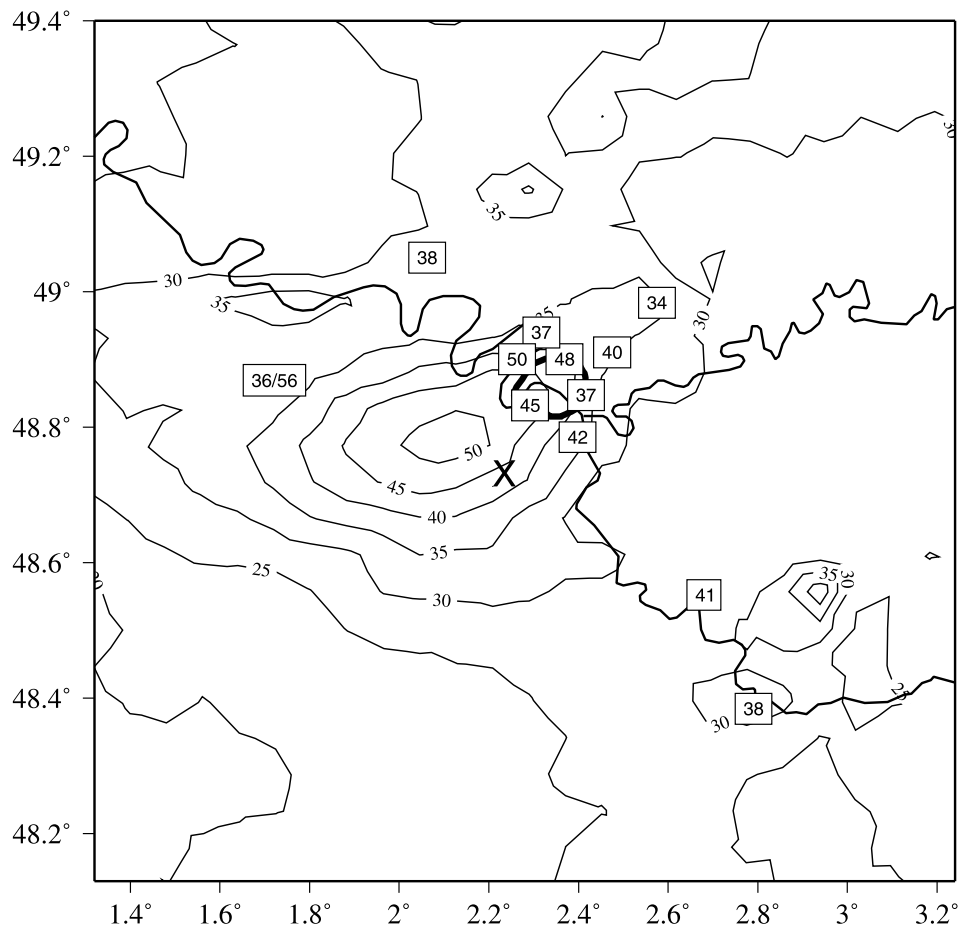


Figure 6. PM₁₀ mean concentrations ($\mu\text{g m}^{-3}$) as computed by CHIMERE model and observed by AIRPARIF network (ground stations indicated by square boxes) for a polluted day between 1100 and 1600 UTC. Palaiseau experimental site is indicated by a cross.

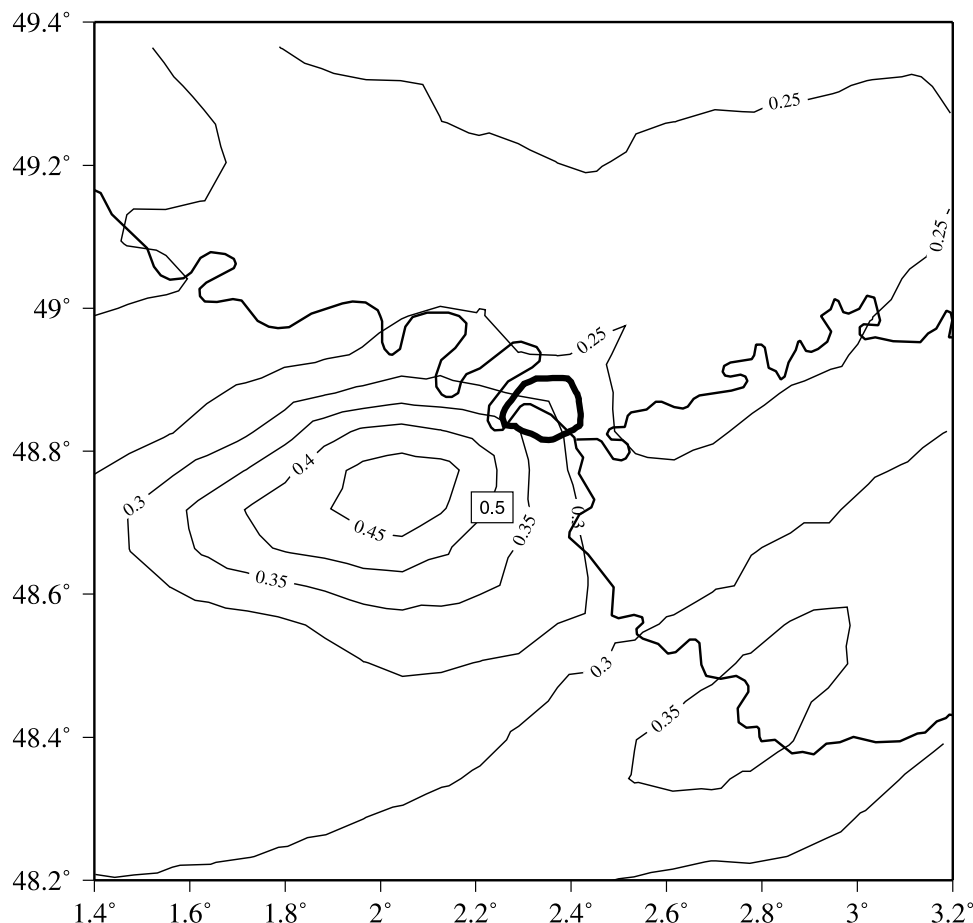


Figure 7. Column integrated aerosol optical thickness computed by CHIMERE model for 26 March 2003 between 1100 and 1600 UTC and observed by Sun photometer located at the site of Palaiseau (square box).

semivolatile material is known to be lost with routinely used devices, like the TEOM monitor used in AIRPARIF stations, and consequently, the PM_{10} concentrations are underestimated by 20% up to 50%, depending on the season and the site [van Loon *et al.*, 2003]. The reference instrument of the Prunay station (about 30 km west of Paris) gives high PM_{10} concentrations (56 instead of $36 \mu\text{g m}^{-3}$) suggesting that the real PM_{10} concentrations are probably underestimated at the others stations. The PM_{10} concentrations retrieved by the model are therefore also probably underestimated.

[40] The aerosol plume is also characterized by its optical signature in the AOT fields (Figure 7). The AOT values simulated by the model reach a maximum of 0.45 inside the plume, because of secondary aerosol formation and particle growth, thus making them more efficient for light extinction. The high AOT values are not located over the center of the city as one could expect, but clearly in the downwind plume. The mean AOT value of 0.5 observed at Palaiseau is comparatively higher than those retrieved by the model.

[41] In order to evaluate the ability of the model to reproduce the daily variation of the aerosols vertical distribution (that depends on the local emissions and atmospheric mixing conditions) we compute the logarithm of the elastic

backscattered lidar range-corrected signal (LRCS) and compare it to the observed one for this particular day. Figure 8 shows a complex vertical structure of the observed atmosphere in the early afternoon by lidar observations. Three different layers can be distinguished: a planetary boundary layer (PBL) that contains the major part of the aerosol load, a residual layer (RL) visible until 1300 UTC, and an aerosol layer located between 2 and 3.5 km particularly well defined in the late morning. The model simulates correctly the vertical structure of the convective boundary layer, but not the thin aerosol layer (between 2 and 2.5 km) and hardly the residual layer. The timing of the development of the boundary layer is fairly well reproduced. The top of the aerosol layer rises from 1 km in the morning to a maximum height of 3 km at 1500 UTC and begins to fall after 1600 UTC.

[42] The hourly mean profiles of the LRCS shown in Figure 9 allow a more accurate comparison between the lidar and the model data. A good agreement between the model and observations is readily seen for the afternoon simulations, even though the model tends to underestimate the aerosol load after 1500 UTC. The morning residual layer also reveals significant underestimations. These underestimations can be due to missing sources in the inventory as well as problems of mixing and advection during

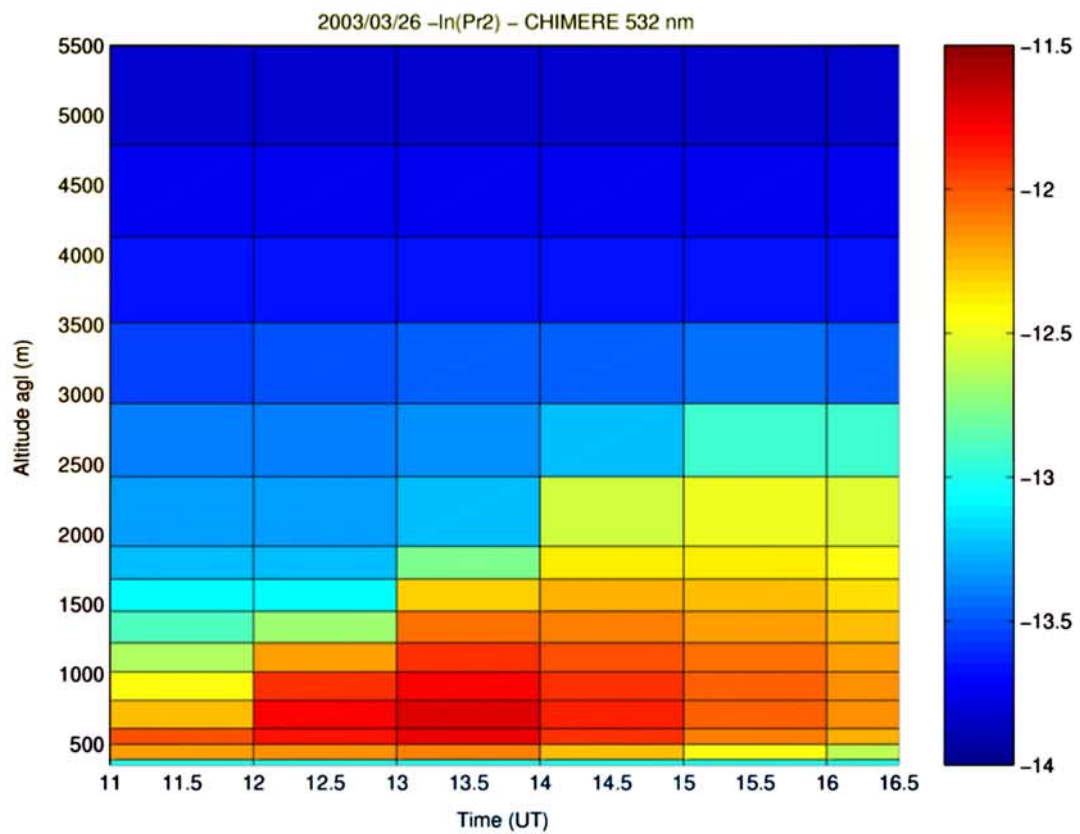
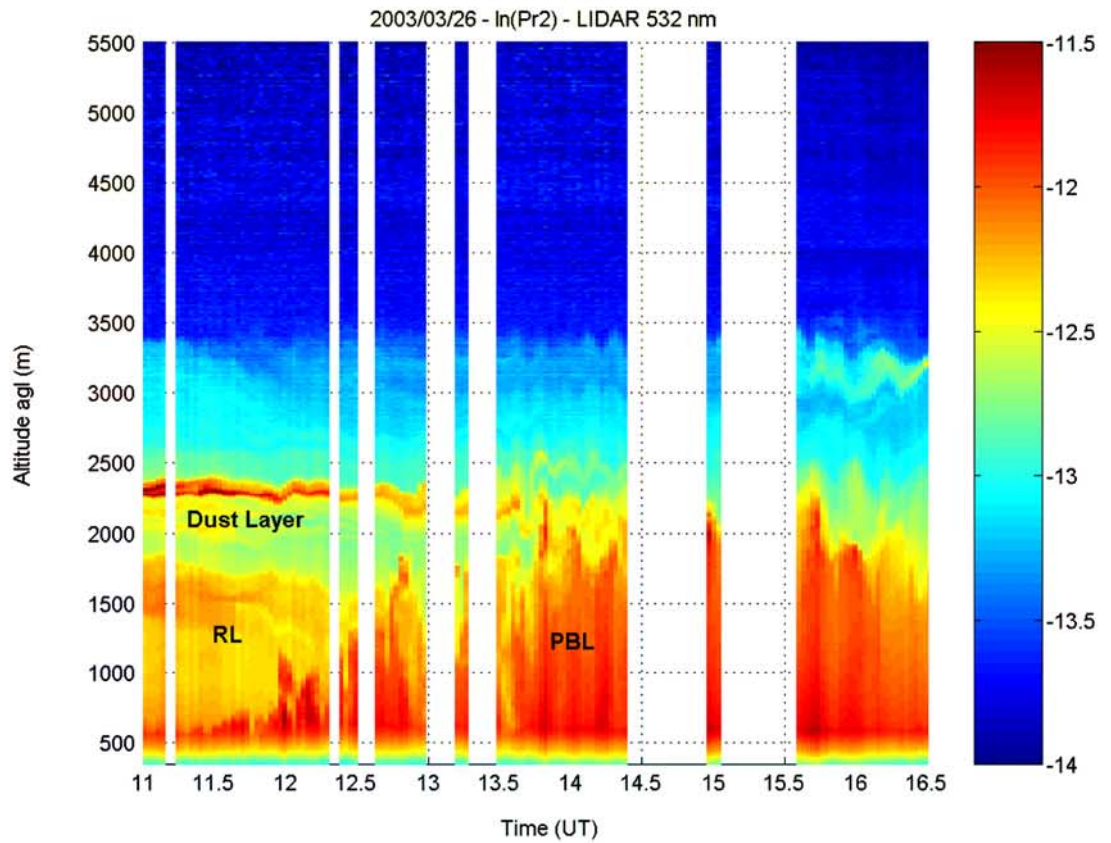


Figure 8

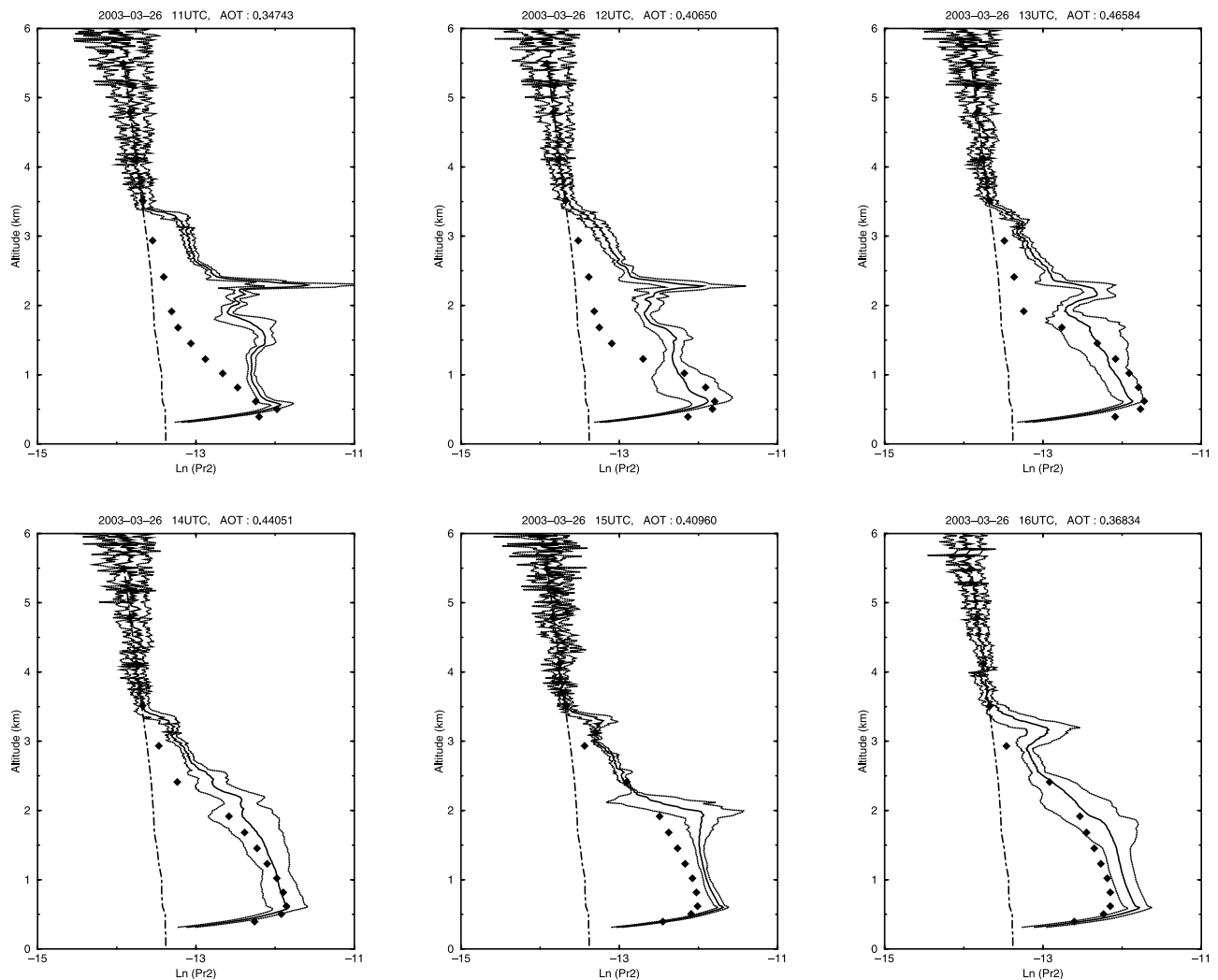


Figure 9. Comparison between the hourly mean backscattering vertical profiles observed by lidar (central solid line) and simulated by CHIMERE (diamonds) at Palaiseau on 26 March 2003 from 0900 to 1600 UTC. The variability of the lidar profile within an hour is also drawn (outer lines). The molecular profile is plotted using a dot-dashed line. Data below 300 m are not plotted because of the visibility restrictions of the lidar near the ground.

nighttime. The thin but concentrated aerosol layer observed between 2 and 2.5 km in the early afternoon is missing in the model simulation. The lidar backscatter profiles display typical signatures of desert mineral dust layers. Furthermore, the lidar linear depolarization ratio is much stronger for aerosol layer observed between 2 and 2.5 km than in the lower aerosol layers, showing that the upper layer is composed of non spherical particles, that is in agreement with a dust origin. The presence of Saharan dust aerosols is consistent with the back trajectories displayed in Figure 10. However, tracking air masses over several days using backtrajectories is difficult, and only a chemical analysis of the aerosol itself would ascertain this result. Saharan

mineral aerosol emission fluxes are not yet accounted for in anyway in our model, and hence they could not reproduce this phenomenon.

6.2. Statistical Analyses

[43] The ability of the model to simulate the aerosol vertical load in the lower troposphere is now assessed by systematic comparisons of the observed and simulated lidar LRCS profiles. Owing to the meteorological conditions and constraints linked to the use of a lidar, there are a limited number of days when the lidar was running and measurements could be taken (Table 6). However, for these days, several hours are available for the comparisons. In order to

Figure 8. Daytime evolution of the vertical distribution of the aerosol lidar range-corrected signal (RCS) at 532 nm, (top) observed by the lidar at Palaiseau during a high air pollution episode of 26 March 2003 and (bottom) simulated by CHIMERE. Various layers, such as planetary boundary layer (PBL), residual layer (RL), and dust layer are also indicated.

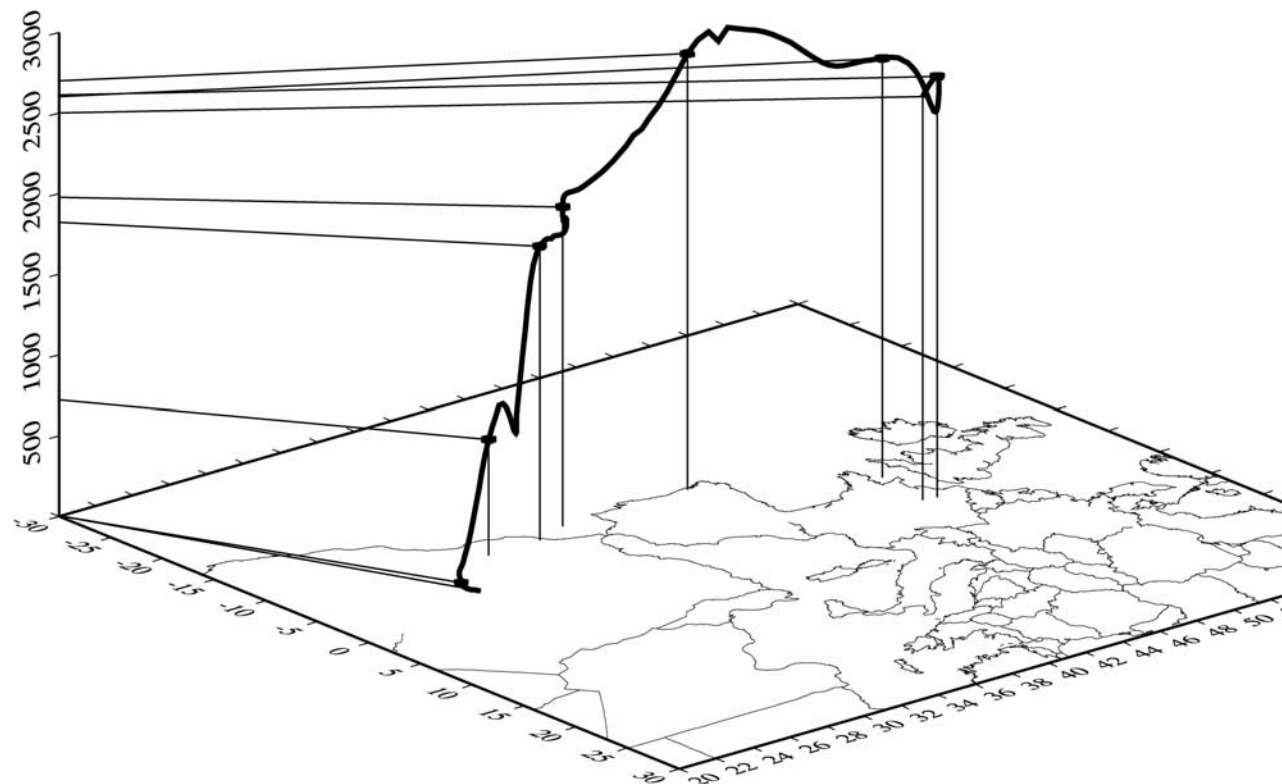


Figure 10. Backward trajectory ending at 1100 UTC 26 March 2003 at Palaiseau, computed using National Oceanic and Atmospheric Administration (NOAA) Hybrid Single-Particle Lagrangian Integrated Trajectory (HYSPLOT) model and FNL meteorological data (courtesy of NOAA Air Resources Laboratory, <http://www.arl.noaa.gov>).

smooth the signal, the lidar profiles are averaged over an hour, and only cloudless data periods are considered in the present study.

6.2.1. Boundary Layer Height

[44] Before comparing optical parameters, we first examine whether the boundary layer height is correctly reproduced by the model on average. For such a comparison we use the lidar and model backscattering profiles. The boundary layer height is taken as the altitude where the signal vertical gradient is strongest [Menut, 1999]. Owing to the occurrence of the multiple aerosol layers in some situations the detection of the boundary layer height is not reliable. Consequently, the number of available data for comparison is limited (67 values for considered profiles). The absence of systematic biases of the model is demonstrated on Figure 11. However, considering the simplicity of this

algorithm and the complexity of real situations, the results contain a large degree of uncertainty.

6.2.2. Mean Profile

[45] In Figure 12, the daily variation of mean backscattering profiles is calculated for both lidar observations and model predictions. The profiles show that the aerosol load

Table 6. Lidar Measurements at Palaiseau Between October 2002 and April 2003 in Cloudiness Conditions

Month	Number of Days	Number of Hours
October 2003	2	8
November 2002	4	6
December 2002	2	8
January 2003	-	-
February 2003	6	23
March 2003	8	44
April 2003	4	19

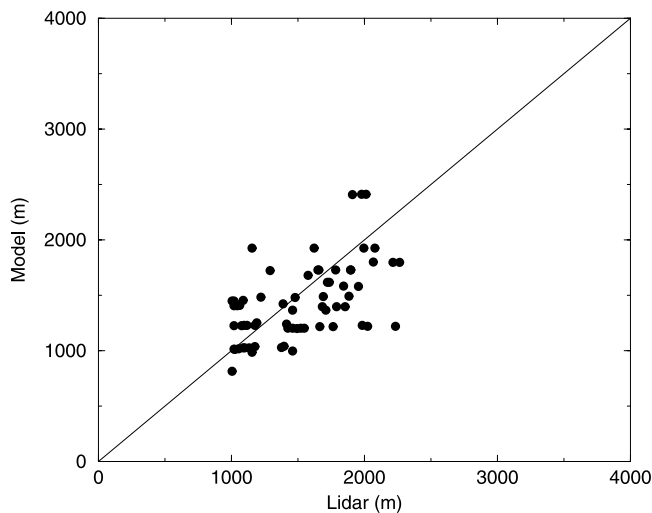


Figure 11. Scatter diagram of lidar-derived versus model-derived boundary layer height for the period from October 2002 to April 2003.

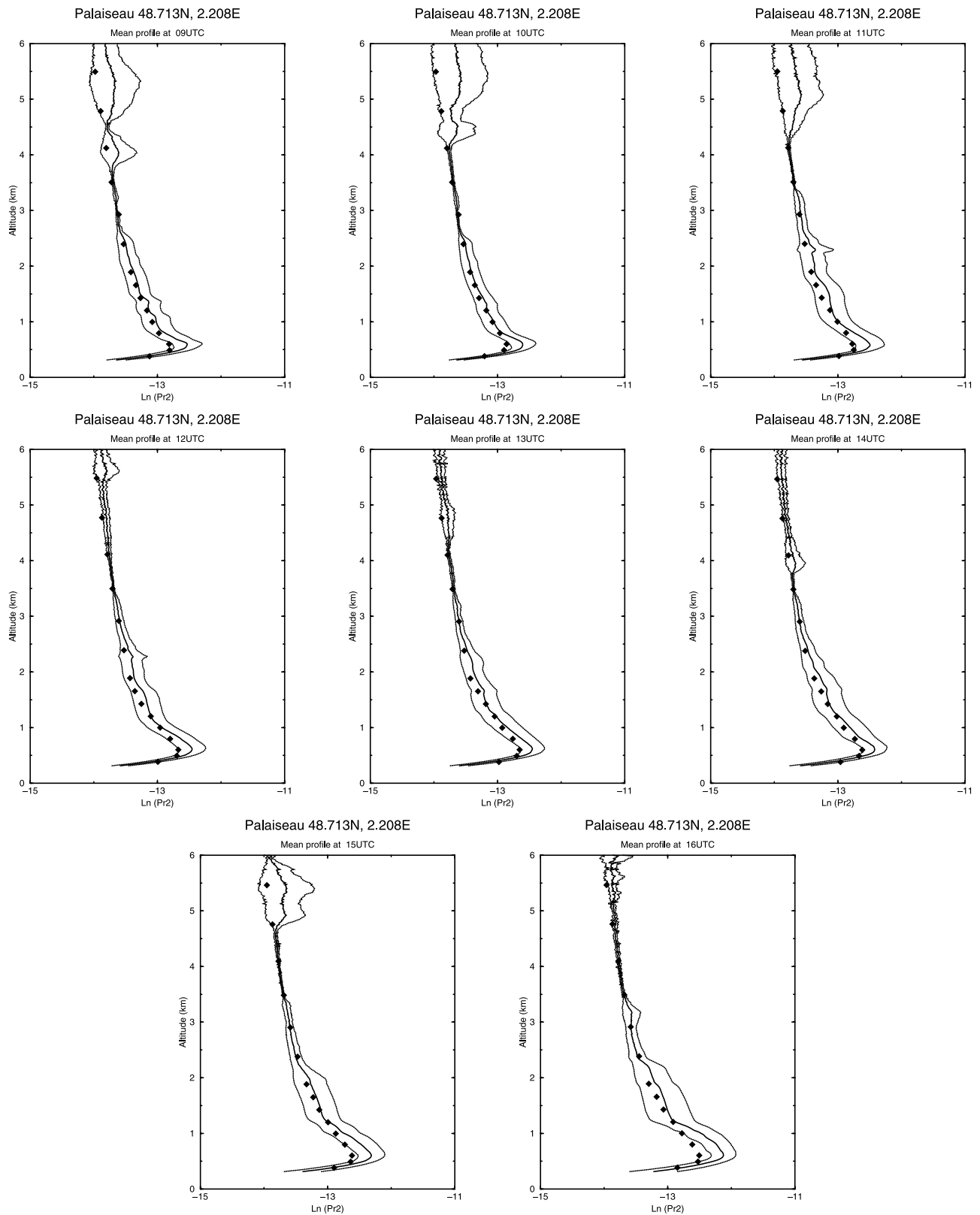


Figure 12. Comparison between the mean hourly lidar RCS vertical profiles observed by lidar (solid line) and the profiles simulated by CHIMERE (diamonds) at Palaiseau between 0900 and 1600 UTC and averaged from October 2002 to April 2003. The error bars are indicated by outer lines. Data are not shown below 300 m because of visibility restrictions of the lidar near the ground.

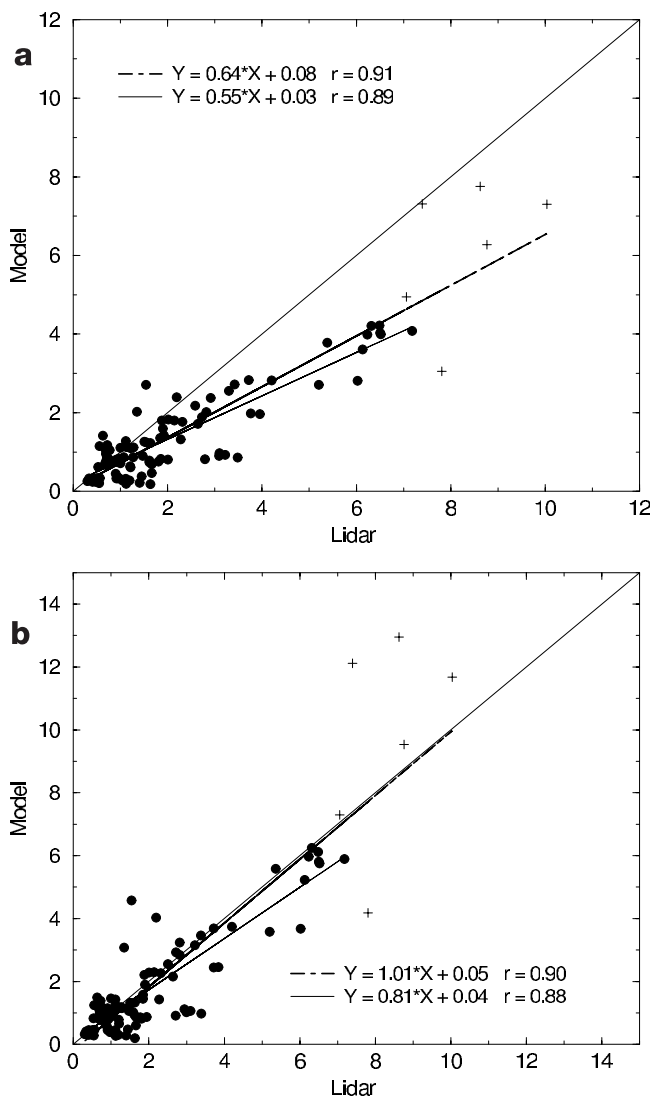


Figure 13. Scatterplot of simulated versus observed integrated Pr^2 values (times 10^{-3}) between 300 m and 3 km from October 2002 to April 2003 for the (a) reference scenario and (b) scenario with increased secondary organic species. Only the aerosol component is compared (the molecular part is not taken into account). The linear regression slope with (black line) and without (gray line) the episode of 26 March and correlation coefficients are also indicated.

accumulates in the boundary layer during the day. The model systematically underestimates the mean lidar profile in the middle of the boundary layer especially during the late afternoon: The aerosol loading is underestimated by more than 20%. However, the model produces a satisfactory shape of the mean vertical profile.

6.2.3. Comparison of Integrated Profiles

[46] In order now to compare the ability of the model to simulate the variability of the profiles, we calculate the integrated Pr^2 lidar values between 300 m and 3 km for each available profile. The scatterplot of simulated versus observed integrated profiles shown in Figure 13a confirms the underestimation of aerosol load by the model within the boundary layer by about 30%, particularly during the

pollution events: The linear regression slope reaches 0.64 for all considered profiles and 0.55 if high values corresponding to the episode of 26 March (influenced by Saharan dust) are excluded.

6.2.4. Comparison for Various Model Levels

[47] In order to avoid possible error compensations in integrated Pr^2 lidar profiles, we also compared lidar and model profiles at various model levels (Figure 14). For the comparison, the lidar values are averaged over the corresponding model layers. According to their altitude, the comparison points can be divided into three groups: points located below 500 m (Figure 14a), affected by the geometric form factor; points within the mixed layer from 500 to about 1500 m (Figures 14b and 14c); and those above 1500 m located in the PBL transition zone (Figure 14d). The very clear underestimation within the mixed layer due to the lack of the aerosol load in the model (Figure 14b) is also present in the transition zone and above the mixed layer (Figures 14c and 14d). The underestimated values in the transition zone generally coincide with the model underestimation of the boundary layer height. Therefore these points (indicated by triangles) are situated within the observed and above the model boundary layer. Figure 14d also shows that the dust layers present on 26 March (indicated by squares) contribute a lot to the model underestimation. The corresponding correlation coefficients vary from 0.71 to 0.92, depending on the model layer.

6.3. Sensitivity Study of the Simulated Lidar Profile

[48] As in section 5, we evaluate here the impact of artificially increasing by a factor 3 the SOA mass and introducing mineral compounds and sea salt on the predicted backscattering profiles. The error statistics presented in Tables 7 and 8 show that the increase of the SOA leads to the better agreement between model and observations within the boundary layer. In this layer and above 500 m, the absolute value of normalized biases decreases from 9 to 12% in the morning and from 7 to 14% in the afternoon. However, in the PBL transition zone, the model underestimation is replaced by an overestimation of the aerosol load, but the dispersion among the observed and simulated values is reduced as suggested by RMS errors. For all layers, the RMS errors generally decrease from 2 to 18%, except at 600 m in the afternoon because of a model overestimation at that level. The correlation coefficient remains high, exceeding 0.7. The improvement of the comparison results by the increase of the SOA is also visible in the integrated profiles (Figure 13b): The linear regression slope reaches 0.81 instead of 0.55 for the reference scenario.

[49] Furthermore, we also find that the impact of the introduction of mineral material and sea salt on lidar backscattering power is less significant, as those particles contribute principally to the coarse aerosol mode which is not very efficient in terms of backscattering at the wavelength of 532 nm. In this case, the decrease of normalized biases and RMS errors is less than 5% in average.

7. Conclusions

[50] In this paper we attempted to provide objective elements for the validation of the vertical structure of the CHIMERE chemistry transport model in its current aerosol

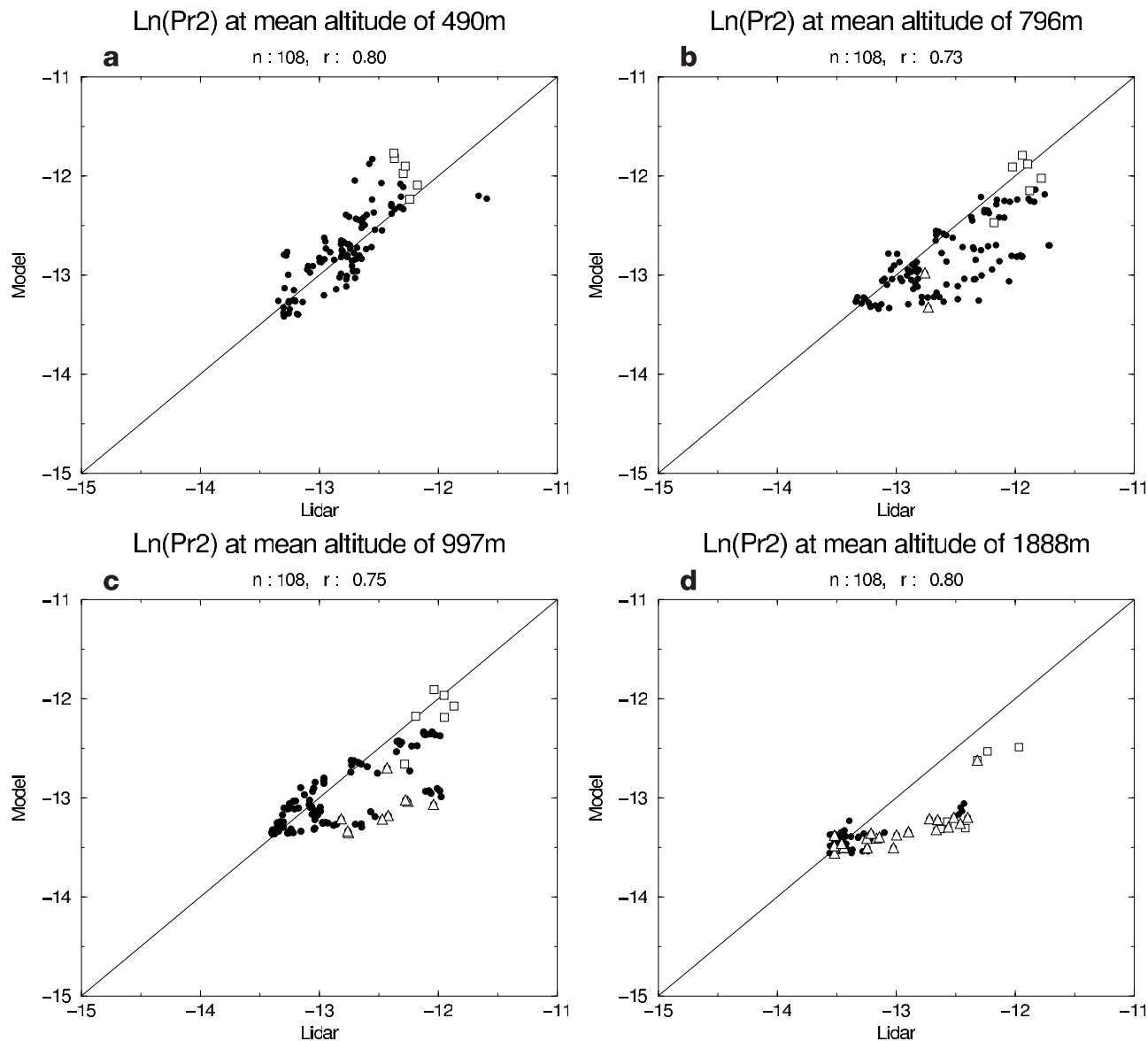


Figure 14. Scatter diagrams of $\text{Ln}(\text{Pr}^2(z))$ as defined by equation (9) for measured versus modeled lidar profiles at different model levels: (a) below 500 m of altitude, (b) in the mixing layer, (c) in the transition zone, and (d) above the PBL top. Points situated above the model boundary layer height (BLH) for which the model underestimates the lidar BLH are indicated by triangles, and the 26 March episode is indicated by squares. Lidar profiles were averaged over the model vertical layers. The number of available data (n) and correlation coefficients (r) are also indicated.

version. The validation is made by comparing a number of elastic volume backscattering lidar profiles over the site of Palaiseau near Paris with their simulated equivalent. The comparison is made directly on the range-corrected backscattering lidar signal. Model simulations are also compared, on monthly averages, with measurements of optical parameters using a Sun photometer. All these comparisons experiments use data collected as often as possible between October 2002 and September 2003.

[51] The model is able to reproduce with reasonable skill both the observed aerosol optical thickness and the vertical elastic backscatter lidar profiles. The comparison with Sun photometer measurements shows that the model tends to underestimate the monthly mean values of AOT by more

than 20% in spring and up to 50% in summer time period. Other optical parameters related to the aerosol composition, such as complex refractive index and single-scattering albedo, are predicted with acceptable errors: They are generally underestimated, except the imaginary part of the refractive index that is overestimated in winter and spring. Above all, this evaluation of aerosol optical properties clearly demonstrates that these latter can be used to simulate an elastic backscattering lidar signal.

[52] The comparison with backscattering lidar profiles allows the evaluation of the ability of the model to simulate the aerosol vertical distribution. First of all, the general shape of lidar signals is quite well simulated on the average, which means (1) that the MM5 meteorological model has

Table 7. Comparison of Observed and Simulated Backscatter Mean Profiles Between 0800 and 1100 UTC at Palaiseau From October 2002 to April 2003 for the Reference Scenario (1), the Scenario (2) With Secondary Organic Species Increased by 300%, and the Scenario (3) Including Mineral Dust and Sea Salt^a

	Altitude, m									
	490	600	796	997	1203	1426	1654	1888	2387	2916
M_{OBS}	0.237	0.715	0.782	0.546	0.392	0.310	0.287	0.219	0.139	0.089
<i>Scenario 1</i>										
Normalized bias, %	1.5	-25.2	-28.7	-15.0	-6.4	-7.4	-29.9	-33.3	-25.0	-46.2
RMS	0.232	0.269	0.350	0.229	0.207	0.167	0.228	0.240	0.227	0.195
Corrected	0.79	0.85	0.79	0.86	0.87	0.94	0.91	0.84	0.84	0.79
<i>Scenario 2</i>										
Normalized bias, %	41.1	-13.4	-19.1	-3.2	7.1	6.5	-18.9	-22.5	-12.6	-37.5
RMS	0.282	0.241	0.316	0.217	0.198	0.137	0.195	0.214	0.204	0.181
Corrected	0.81	0.86	0.78	0.85	0.88	0.95	0.91	0.92	0.87	0.83
<i>Scenario 3</i>										
Normalized bias, %	26.1	-18.1	-23.1	-8.8	0.1	-1.2	-25.2	-29.0	-20.3	-43.3
RMS	0.252	0.247	0.324	0.217	0.203	0.156	0.214	0.232	0.222	0.191
Corrected	0.79	0.85	0.79	0.86	0.87	0.94	0.91	0.84	0.83	0.79

^aThe molecular component is not taken into account. Under 500 m the comparison depends on the geometric factor and is not really significant. Number of samples is 40.

no particular bias in simulating the daytime height of the boundary layer and (2) that the mixing rate within the boundary layer is such that the aerosol mean vertical distributions are represented correctly. Second, there is a clear underestimation of the lidar signal within the boundary layer and above. Many factors could lead to such a behavior. The primary anthropogenic emissions may be underestimated, in which case one should in principle observe a rather seasonally uniform bias. Such is not the case: The bias is much higher in summer than in winter. Therefore processes typical to summertime aerosol formation can be incriminated such as secondary organic aerosol formation and dust emission by wind erosion of dry soil. Our knowledge about the first process is highly uncertain, and wind blown dust is not accounted for in our model. We also performed sensitivity experiments showing that both

processes could be responsible for the model bias. However, the missing mineral components (mineral dust and sea salt) composed principally of coarse particles are not the primary cause of the underestimation as they are not efficient in terms of aerosol optical properties: The coarse modes account for less than 7% of the backscattering effect at 532 nm, while the accumulation mode (particles from 0.08 to 1.25 μm in radius) accounts for more than 89%. Finally, the aerosol load bias above the boundary layer is probably due to several factors, among which the lack of long-range transport of fine Saharan dust in the model. Such a bias could also stem from insufficient exchange between the boundary layer and the free troposphere, because of a too rough parameterization of turbulent processes in the model. We detailed an example (26 March 2003) that illustrates all these problems.

Table 8. Comparison of Observed and Simulated Backscatter Mean Profiles Between 1200 and 1600 UTC at Palaiseau From October 2002 to April 2003^a

	Altitude, m									
	490	600	796	997	1203	1426	1654	1888	2387	2916
M_{OBS}	0.319	0.827	1.002	0.864	0.643	0.437	0.352	0.310	0.228	0.110
<i>Scenario 1</i>										
Normalized bias, %	30.0	-13.3	-23.2	-22.3	-17.6	-3.3	-13.0	-29.5	-34.2	-34.6
RMS	0.325	0.255	0.384	0.371	0.329	0.219	0.216	0.263	0.259	0.170
Corrected	0.73	0.83	0.69	0.73	0.76	0.88	0.92	0.88	0.78	0.68
<i>Scenario 2</i>										
Normalized bias, %	84.0	5.7	-9.4	-9.5	-4.5	11.9	0.9	-18.2	-24.4	-25.7
RMS	0.448	0.307	0.365	0.359	0.321	0.212	0.178	0.223	0.235	0.160
Corrected	0.75	0.83	0.70	0.73	0.77	0.89	0.93	0.89	0.80	0.71
<i>Scenario 3</i>										
Normalized bias, %	50.6	-6.0	-17.8	-17.0	-12.1	3.0	-7.4	-24.9	-29.8	-30.3
RMS	0.357	0.245	0.359	0.354	0.320	0.216	0.203	0.249	0.251	0.167
Corrected	0.73	0.83	0.70	0.73	0.76	0.88	0.92	0.88	0.78	0.69

^aThe molecular component is not taken into account. Number of samples is 68.

[53] In our study showed that the backscatter lidar provides very useful information on the quantitative determination of the aerosol load in the lower troposphere and allows the validation of mesoscale aerosol models. This work, performed only at one particular site, calls for a generalization of the comparisons to other European lidar measurement sites in frame of the EARLINET project situations [Bösenberg *et al.*, 2003], and thus it could be promising for the use of space-borne lidar systems (e.g., CALIPSO validation).

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- M. Beekmann and P. Drobinski, Service d'Aéronomie, Institut Pierre-Simon Laplace, 75252 Paris, France.
- B. Bessagnet, Institut National de l'Environnement Industriel et des Risques (INERIS), 60550 Verneuil en Halatte, France.
- B. Chatenet, Laboratoire Interuniversitaire des Systèmes Atmosphériques, 94010 Créteil, France.
- P. Chazette, Laboratoire des Sciences du Climat et de l'Environnement, Institut Pierre-Simon Laplace, 91191 Gif sur Yvette, France.
- H. Chepfer, J. Cuesta, M. Haefelin, A. Hodzic, Y. Morille, and R. Vautard, Laboratoire de Météorologie Dynamique, Institut Pierre-Simon Laplace, Palaiseau Cedex 1 91128, France. (hodzic@lmd.polytechnique.fr)
- P. Goloub, Laboratoire d'Optique Atmosphérique, 59655 Villeneuve d'Ascq, France.